Voice-Activated Robotic Exoskeleton for Rehabilitation and Assistance (#8130)

An automated robotic exoskeleton that allows patients to perform rehabilitation within the home setting

Inventors at Georgia Tech have developed an automated robotic exoskeleton that allows the patients to perform rehabilitation within the home setting. The voice-activated device will enable patients to control the exoskeleton without relying on mechanical buttons. It automatically modifies the therapy plan as the patient progresses while relaying improvement data (quantitative performance metrics) to the medical provider through its integrated smartphone application. This invention has the potential to improve rehabilitation by allowing the patient to stimulate recovery by regularly performing exercises outside of the physical therapy clinic.

Importantly, the exoskeleton allows the patient to perform exercises at home that are recommended by the physical therapist who can monitor the patient remotely through the device’s integrated smartphone application.

Benefits/Advantages

- Voice-activated movement controlled by the patient
- Integrated smartphone application to recommend exercises and schedules
- Quantitative performance metrics and analysis sent to the physical therapist
- Customizable via 3D printing to accommodate various anatomies

Potential Commercial Applications

- Patients suffering from upper body motor dysfunction: Stimulate recovery at home under the guidance of a medical provider
- Patients with degenerative diseases, stroke, and trauma injury: Ongoing recovery outside of the clinic

Background/Context for This Invention

More than 20 million people in the US suffer from some form of motor disability often as a result of neurological conditions like cerebral palsy, Parkinson’s disease, stroke, spinal cord injury and multiple sclerosis. Rehabilitation via physical therapy is standard of care and vital for recovery, but improvement is often slow due to limited availability of therapy sessions. Hence, there is an unmet medical need to increase the frequency of therapy for patients suffering from motor impairment to provide faster recovery and improved quality of life.
Jaydev P. Desai  
Director, RoboMed Laboratory and Professor -  
Georgia Tech Wallace H. Coulter Department of Biomedical Engineering

Seokhwan Jeong  
Post-Doctorate - Georgia Tech Department of Biomedical Engineering

Phillip Tran  
PhD Student - Georgia Tech Department of Biomedical Engineering

Xuefeng Wang  
Postdoctoral Fellow - Georgia Tech Department of Biomedical Engineering

Towards the development of a voice-controlled exoskeleton system for restoring hand function, 2019  
International Symposium on Medical Robotics (ISMR), April 2019

Patient-Specific, Voice-Controlled, Robotic FLEXotendon Glove-II System for Spinal Cord Injury,  
IEEE Robotics and Automation Letters, April 2020
For more information about this technology, please visit:
https://licensing.research.gatech.edu/technology/voice-activated-robotic-exoskeleton-rehabilitation-and-assistance